Article

Landslide Identification and Monitoring along the Jinsha River Catchment (Wudongde Reservoir Area), China, Using the InSAR Method

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Abstract: Landslide identification and monitoring are two significant research aspects for landslide analysis. In addition, landslide mode deduction is key for the prevention of landslide hazards. Surface deformation results with different scales can serve for different landslide analysis. L-band synthetic aperture radar (SAR) data calculated with Interferometric Point Target Analysis (IPTA) are first employed to detect potential landslides at the catchment-scale Wudongde reservoir area. Twenty-two active landslides are identified and mapped over more than 2500 square kilometers. Then, for one typical landslide, Jinpingzi landslide, its spatiotemporal deformation characteristics are analyzed with the small baseline subsets (SBAS) interferometric synthetic aperture radar (InSAR) technique. High-precision surface deformation results are obtained by comparing with in-situ georobot measurements. The spatial deformation pattern reveals the different stabilities among five different sections of Jinpingzi landslide. InSAR results for Section II of Jinpingzi landslide show that this active landslide is controlled by two boundaries and geological structure, and its different landslide deformation magnitudes at different sections on the surface companying with borehole deformation reveals the pull-type landslide mode. Correlation between time series landslide motion and monthly precipitation, soil moisture inverted from SAR intensity images and water level fluctuations suggests that heavy rainfall is the main trigger factor, and the maximum deformation of the landslide was highly consistent with the peak precipitation with a time lag of about 1 to 2 months, which gives us important guidelines to mitigate and prevent this kind of hazard.

Keywords: InSAR; landslide identification; landslide monitoring; landslide type inversion; interferometric point target analysis (IPTA)

1. Introduction

Water level fluctuation due to dam construction is a main landslide trigger factor [1]. In turn, the waves generated by landslide threaten the safety of the dam, loose pulley and local residents, which have been studied as a typical case in Three Gorges Dam, China [2]. There are four hydropower stations on the lower reaches of the Jinsha River, among which Wudongde Hydropower Station is the extra-large hydropower project. Therefore, a landslide in the Wudongde reservoir area along Jinsha River catchment will potentially threaten the safety of the hydropower station and the people who
live in the lower reaches. Landslide inventory mapping at the catchment scale is the prerequisite for landslide stability analysis, hazard evaluation and risk assessment [3], which refers to the spatial locations of landslides for hazard assessments [4,5]. In particular, the detection of large and active instable bodies is much more important since these creep bodies can change to sudden movements such as rock falls, landslides or earth flows [6]. Nowadays, many different landslides detection techniques have been developed including traditional survey and investigation methods, such as tilting, spirit leveling, GPS, optical remote sensing [7,8], and advanced interferometric synthetic aperture radar (InSAR) owing to its high precision, high spatial (and even temporal) resolution, broad coverage and operation under all weather conditions [9].

The InSAR technique has been used for landslide location detection and landslide deformation monitoring [10–16]. Various InSAR techniques have been employed, including the traditional differential InSAR method [17–19], small baseline subsets (SBAS) InSAR method [20], corner reflector InSAR [21,22], persistent scatterer InSAR technique [23,24], squeeSAR technique [25] and ground-based InSAR technique [26]. However, InSAR-based landslide identification is still a challenging topic, especially in remote mountainous areas without a priori information due to temporal and volume decorrelation, atmospheric artefacts and digital elevation model (DEM) error [27–29]. To solve these shortages, multi-temporal InSAR technology has been successfully validated [27]. In this study, interferometric point target analysis (IPTA) is applied to calculate the annual deformation rate map in coherent regions since it can reduce the atmospheric delay, baseline error and DEM error iteratively with the assumption of a linear deformation model [30–32]. The SBAS method is used to obtain time series deformation results without any deformation model assumption [20,32].

The types of and the external influential factors are decisive for the prevention and control of landslides. It is very important to make reasonable analysis based on the monitoring results combined with the geological data. For example, Schlögel et al. [33] found that InSAR deformation could reflect the different types of landslides. Kang et al. [16] analyzed the pre-sliding deformation of Guanling landslide with advanced land observing satellite (ALOS) phased array type L-band synthetic aperture radar (PALSAR) data and discussed the mechanism of the landslide failure mode. Zhang et al. [34] monitored the deformation of the Shuping landslide with the InSAR technique and suggested that the fluctuation of the Yangtze River water level was the main influential factor of landslide instability. In this study, some comprehensive analyses for the type and trigger factors of the landslide are made by combining phase-based surface deformation, intensity-based soil moisture and the water level measurements.

2. Background

Wudongde Hydropower Station, located in the lower reaches of the Jinsha River in the southwest of China (Figure 1), is one of the key components of the west-east electricity transmission project, which can be used not only for the power generation but also for flood control and sediment flushing [35]. The south bank of the Wudongde reservoir area belongs to Luquan County, Yunnan province, while the north bank belongs to Huidong County, Sichuan province [36]. The reservoir area is located on the southeast border of the Qinghai Tibet Plateau, which is the transition zone between the southwest Sichuan mountain area and the Yunnan-Guizhou Plateau. The study area belongs to the Zhongshan landform, which is affected by tectonic activity and river erosion [37]; therefore, geological disasters occurred frequently in this area [36]. The geomorphology of the study area is much more complex; the lowest area is the valley of Jinsha River, and the depth of the valley generally ranges from 800 to 2000 m, while the altitude of the mountain peak on both sides of the valley ranges from 2500 to 2800 m.

The northwest, southwest and southeast sides of the study area are adjacent to the Songpan-Ganzi Fold System, the Sanjiang Fold System and the Southern China Fold System, respectively [38]. The research area has been influenced by the strong activities of the Western Geosyncline in history, and the folds and faults are well developed. The Bedrock of lower Sinian system of the Neoproterozoic to Mesozoic Upper Cretaceous System and the Quaternary deposits in the Cenozoic are distributed
in the study area, and the Quaternary deposits are mainly distributed in the valleys and gentle terrain areas [36–38].

The climate of the study area belongs to the subtropical monsoon climate. From the bottom of the valley to the top of the mountain, the climate zones present as Pingba dry and hot valley, hilly and low mountain warm zone, Zhongshan warm area and mountain warm area, etc. [36]. The vegetation includes savannah, pine forest and broadleaf forest. However, the ecological environment has been severely damaged due to deforestation. Most of the area is bare wasteland under the altitude of 2000 m, which is one of the key environmental factors affecting the occurrence of debris flow [36]. Two seasons, namely, dry and rainy seasons, are common in this area; heavy rain and rainstorm weather occurs mainly in the rainy season from May to September, especially from June to August, and extreme rainstorms often result in mudslides, landslides and other disasters [37].

3. Data and Methods

3.1. Data

Twenty L-band archived ALOS/PALSAR images spanning the period from January 2007 to March 2011 with ascending track are included in this study. The interferograms from L-band SAR data have higher coherence than those from the C-band and X-band for the vegetated terrain [39].

To keep the same pixel size between fine-beam double polarization (FBD) and single polarization (FBS) ALOS/PALSAR data, the former is firstly oversampled twice in the range direction. Secondly, to try to detect moderate to small-scale landslides and to map landslides with large deformation, two multilook numbers (One-pixel size is about 7.5 × 7.5 m) are set to generate SAR interferograms [40]. One arc-second shuttle radar topography mission (SRTM) DEM with a pixel size of 30 m is adopted to remove the topographic phase and for the final results analysis.

The temporal baseline and the perpendicular baseline thresholds are set to 720 days and 1250 m, respectively. Because the long perpendicular baseline took place in the middle of 2008 for ALOS-1 SAR data, multiple master SAR interferometric pairs are generated. Then, interferograms with heavy atmospheric artefacts and unwrapping errors are visually checked and removed [41,42]. Finally, 31 interferograms are retained as shown in Figure 2, where dashed lines indicate removed interferograms.
Figure 2. The combination of synthetic aperture radar (SAR) interferometric pairs with respect to the temporal and spatial baselines, where solid lines show accepted interferograms, while dashed lines indicate removed interferograms.

3.2. Flowchart of Landslide Identification and Monitoring

For an unknown region, landslides are firstly identified based on an InSAR-derived deformation map. Then, for a specific landslide, time series deformation will be monitored to obtain a deep understanding of the landslide activities. The flowchart of landslide identification and time series deformation monitoring with InSAR techniques is shown in Figure 3.

Figure 3. The flowchart of landslide identification and monitoring with InSAR methods. In the flowchart, PS stands for persistent scatterer, DEM is digital elevation model and RS means remote sensing.
3.2.1. Persistent Scatterer Selection

As most landslides occurred in the mountainous regions, the prerequisite for landslide detection is to determine the target points with high quality and a certain density. In this test, three strategies are used to determine Persistent Scatterer (PS) points, namely, spectral diversity [30], amplitude dispersion index and the phase stability [23,43]. Firstly, two sets of PS candidates with low spectral diversity and low amplitude dispersion index are acquired and merged. In addition, PS candidates with low phase stability will be eliminated through two-dimensional regression analysis. Thus, high-quality PS points will be retained.

3.2.2. Landslide Identification

Firstly, IPTA SAR data processing is used to acquire the deformation map [30]. Once the PS points are determined, the wrapped differential phase of PS points on the multi-temporal data stack is calculated with the aid of SRTM DEM, which is interpolated to the slant range radar image coordinate. The linear deformation rate map is generated by the IPTA method. Then, landslides are identified based on the deformation patterns, which can be plotted onto DEM and/or optical remote sensing images. The DEM is mainly used to calculate the slope of the terrain. The areas with a slope angle less than 10 degrees are not considered as landslides in this case. Optical satellite imagery (e.g., Google earth images) is used to determine the landslide boundary. During the specific InSAR monitoring period, obvious deformation may only occur in some parts of the landslide region, which can hardly outline the whole landslide; even some groove and crack or the discontinuity of a stratum can be seen on the spot and can be delineated from the optical satellite imagery [44,45]. In this test, Google earth images are used to roughly depict the extent of the active landslides, which are guided by the InSAR deformation patterns. The main processing steps are summarized as follows:

Step 1. Phase unwrapping. The Minimum Cost Flow (MCF) algorithm based on the Delaunay triangulation network is used for phase unwrapping, i.e., the Delaunay triangulation network is generated based on sparse coherent points [46]. Only unwrapped interferograms can be used to refine the spatial baseline and separate the atmospheric phase.

Step 2. Baseline refinement. In this step, an initial estimation of the linear deformation rate and residual phase is acquired through 2-dimensional (2D) linear regression under the IPTA framework. Then, the terrain phase is added back to the unwrapped differential interferograms, followed by the least square estimation of baseline parameters upon GCPs (Ground control point), from which both the unwrapped phase and corresponding elevation are extracted [47].

Step 3. Atmospheric phase delay (APD) and DEM error estimation. After the baseline refinement, differential interferogram, phase unwrapping, and 2D regression analysis is conducted again. The updated linear deformation rate and DEM error are acquired. The APD can be derived from the residual phase using spatial and temporal filtering [29]. Then, the interferograms are updated by the correction of APD and DEM error.

Step 4. Deformation calculation of PS points. In this step, the linear deformation rate of PS points is calculated by 2D regression analysis of the updated interferograms.

Step 5. Suspected landslides mapping. According to the deformation patterns and combined with SAR geometry, e.g., look angle, DEM and optical remote sensing images, locations and extents of the suspected landslides can be mapped.

3.3. Landslide Time Series Deformation Monitoring

Due to the small volume of SAR data, the SBAS-InSAR method is applied to retrieve the continuous deformation field in the spatial domain and time series deformation in the time domain for the specific landslide [20]. The differential interferograms are divided into high-quality sets and low-quality sets. The former are used to estimate the DEM error. After the DEM error correction, all interferograms are used to estimate the average deformation phase and the phase for each SAR
acquisition date. As the atmospheric phases are spatially correlated and temporally random, the APD can be separated through low-pass filtering and high-pass filtering in the space and time domains, respectively [29]. The remainder is the nonlinear deformation phase, which can be added back to the average deformation phase, and the cumulative deformation can be trivially acquired for each SAR acquisition date. In most cases, the earliest SAR acquisition date is set as the reference date. The abovementioned procedure is conducted in single datasets with least square criteria. Once there is more than one dataset, the deformation between adjacent datasets has to be constrained by some smooth assumption or given by the external measurements.

4. Results and Analysis

4.1. Landslides Identification Results

The InSAR products including intensity maps and coherence maps and external DEM could be used to detect and map landslides that occur suddenly with a certain extent [48], while the deformation map is beneficial to identify the potential, slow, and long-term deformed landslides. In this experiment, twenty-two landslides covering an area of approximate 2500 km² are identified from the InSAR derived deformation map, as shown in Figure 4. As the deformation is illuminated in the line-of-sight (LOS) direction, please note that the red in Figures 4a and 5 indicates the movement close to the sensor, while the blue is away from the sensor. Figure 4b shows the suspected landslide locations. It is obvious that most of the suspected landslides are developed on both sides of the valley, which can be explained by the special geomorphology. The valley of Jinsha River, deep and narrow with a 500~2000 m cutting depth, affected by strong water erosion, forms the landslide-prone region.

As landslides are often constrained by topography, optical images can be used as the background for landslide boundary delineation and the deformation illustration, on which the whole landslide including active or inactive regions can be seen with discontinuous landforms [44,49]. Landslides in 6 regions in Figure 4a are enlarged and superimposed on perspective Google earth images, shown in Figure 5. It can be found that the obvious features of landslide and debris flow gully, such as a groove and a crack can be seen clearly from the Google earth images.

![Figure 4. Cont.](image-url)
Figure 4. Deformation map and the locations of suspected landslides over the Wudongde reservoir area. (a) Deformation map generated by the interferometric synthetic aperture radar (InSAR) method; (b) Landslide location map.

Figure 5. Enlarged deformation rate maps of detected landslides superimposed on Google earth images; the color bar is same as in Figure 4. Graphs (a–f) correspond to the area A to F marked in Figure 4a. The white curve in each graph is the approximate boundaries of the suspected landslides.
In order to further confirm the identified suspected landslides, published literature was reviewed [35–37,50–52], and 9 of the 22 landslides have already been documented as follows: No. 10 in Figure 4 is the Yangpingzi unstable rock mass, No. 11 is the Huashan landslide, No. 13 is the Qianchang unstable rock mass, No. 14 is the Dacun-Fujiapingzi landslide, No. 15 is the Dapingdi landslide, No. 16 is the Jinpingzi landslide, both No. 17 and 18 belong to the Shuanglongtan debris flow, and No. 20 is the Pufu landslide. It should be noted that the abovementioned landslides are recorded due to their prior occurrence; other suspected landslides that have not been found in the relevant literature might be potential landslides, which means much more attention should be given to prevent or reduce the hazards.

4.2. Landslide Deformation Monitoring Analysis

Jinpingzi landslide, labeled as No. 16 in Figure 4b, which is focused on to show spatial and time series deformation features, is settled on the right bank of Jinsha River in the lower reach of the Wudongde Hydropower Station. The landslide is divided into 5 sections according to its topography, geomorphology and geological features shown in Figure 6a as follows, Dangduo ancient accumulation (Section I), creep accumulation (Section II), Jinpingzi ancient accumulation (Section III), in-situ bedrock (Section IV) and bedrock outcrops (Section V) in the leading edge of the Jinpingzi ancient accumulation [51]. The elevation of the leading edge is about 820 m, and the elevation of the trailing edge ranges from 1900 m to 2200 m. The total volume of the landslide is about 620 million cubic meters [51]. Section II is the most unstable block among these sections, which has been monitored with in-situ equipment for a long time [37,51]. The slope of Section II is from 18 to 36 degrees (the average slope angle is about 23 degree), and the total volume of this section reaches 27 million cubic meters. Once this section slumps, a tremendous disaster will occur.

![Figure 6. Jinpingzi landslide maps (a). Zonation map of Jinpingzi landslide, including Section I, Dangduo ancient accumulation with a total volume of 60.5 million m³; Section II, creep accumulation with a total volume of 27 million m³; Section III, ancient accumulation with a total volume of 108 million m³; Section IV, in-situ bedrock; Section V, in-situ bedrock. The red line represents the faults. (b) Average deformation rate map in the downslope direction over Section II of the Jinpingzi landslide, where two triangles represent the ground monitoring points used for the following analysis, and the square represents the drill holes. The dashed lines from AA’ to EE’ denote profile locations. The black lines indicate slide-bounding strike-slip fissures.](image-url)
4.2.1. Deformation Results

Archived SAR data spanning the period from January 2008 to March 2011 are considered to obtain the time-series deformation over Jinpingzi landslide through the SBAS-InSAR technique. Fifteen pairs of high quality interferograms are used for time series deformation monitoring after removal of low quality interferograms, which belongs to three subsets as shown in Table 1. Then, the LS norm is used to obtain the time-series deformation for each subset, and the average deformation rate is acquired by the stacking interferogram method [53].

Table 1. The parameters of interferometric pairs for landslide deformation monitoring.

<table>
<thead>
<tr>
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<th>Perpendicular Baseline (m)</th>
<th>Interval</th>
<th>Subset</th>
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<td>404</td>
<td>46</td>
<td>1</td>
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<tr>
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</table>

In order to reveal the spatiotemporal characteristics of landslide deformation, the line-of-sight deformation is projected in the slope direction [16]. The average deformation rate map of Jinpingzi landslide in the downslope direction is shown in Figure 6.

4.2.2. Spatial Deformation Characteristics

It can be seen in Figure 6b that the surface deformation in the leading section of the landslide was larger than that in the trailing section. Accordingly, this landslide may belong to a pull-type landslide. The maximum downslope deformation rate occurred at the southernmost corner of the leading section, which reached 39 cm/year.

The deformation rate and the terrain of the landslide are extracted along four transverse lines, as shown in Figure 7. It can be seen that the width of landslide gradually decreases from the trailing section to the leading section. The deformed region is controlled by two boundaries, where several slide-bounding strike-slip fissures can be detected as shown in Figure 6a. In Figures 6 and 7, abrupt deformation changes can be obviously seen across some parts of boundaries, which is similar to the strike-slip fault deformation [54]. Especially in Figure 7c,d, the deformation rate suddenly drops from 30 cm/y to 0 cm/y within 20 m crossing the boundaries, and the obvious discontinuity of these boundaries can be seen in the Google image. This kind of boundary, i.e., similar to strike-slip faults, has been found in some other landslides detected by field investigation or geophysical prospecting method [55–58]. The slidequake generation is generally correlated with these boundaries, which play a significant role in the landslide movement [58]. In this paper, this kind of boundary can be clearly mapped from the InSAR deformation map (as shown in Figure 6).
Figure 7. Cross-sections of annual landslide slip rate in the downslope direction along (a) profile AA’; (b) profile BB’; (c) profile CC’ and (d) profile DD’ marked in Figure 6. The solid curve shows the elevation in each panel; error bars represent the standard deviations of the estimated slip rate. The boundaries of Section II of the Jinpingzi landslide are indicated with dashed lines at the top of each figure, and the red dashed lines represent the slide-bounding strike-slip fissures.

On the other hand, it can also be seen that the transverse topography gradually transformed from concave terrain to convex terrain from the trailing section to the leading section of the landslide (as shown in Figures 6a and 7), indicating that the materials were deposited in the leading section from the trailing section during the long-term landslide creeping.

In addition, it can be found that the deformation at the leading edge of Section II changed very sharply; quantitatively speaking, the maximum cumulative deformation changed quickly from $-45$ to $0$ cm within 100 m, which indicates that the exposed bedrock in front of Section II prevents the landslide movement. Secondly, due to the wedged shaped landslide with a narrow leading section and wide trailing section, the boundaries on both sides of the landslide have anti-slip force relative to the landslide. Furthermore, the fault in front of the landslide plays a key role in landslide deformation.

4.2.3. Comparison of Interferometric Synthetic Aperture Radar Deformation with Georobot Measurements

Section II of the landslide has been continuously monitored with georobot since January 2005 [59,60]. The total displacement of each georobot monitoring point is compared with the InSAR deformation in the downslope direction. Firstly, the slip rate results over seven georobot benchmarks are compared with InSAR measurements from Sep. 2009 to Mar. 2011 (the third monitoring subsets are presented in Table 1, and the time series deformation of the third subsets is shown in Figure 8.
As shown in Figure 9, the error bar of the InSAR results represent the uncertainty with RMS (root mean square error) of the slip rate results within the region of the 50 m × 50 m area around the georobot monitoring point. We find that the largest difference is located at TP14, which has reached 2.6 cm/y. Except for TP10 and TP14, the difference of the other five points is less than 1.3 cm/y. To compare InSAR measurements with georobot measurements, all InSAR deformation in LOS is transferred to the landslide downslope direction using uniform landslide geometry. However, the local landslide movement directions are slightly different in different parts; therefore, discrepancies for some points can be found.

Then, time series InSAR and georobot monitoring results from 2007 to 2011 are compared at two benchmarks of points TP04 and TP08. Since the datum of the deformation sequence acquired by the georobot is different from the one acquired by InSAR, the initial offsets of each InSAR subset
are considered with respect to the time series deformation measured by georobot. It is clear that the time series deformations acquired by InSAR are strongly consistent with georobot measurements. Considering the locations of points TP04 and TP08, the surface deformation at the lower terrain (TP04) was larger than that at the higher terrain (TP08), while the two points have similar deformation trends from 2007 to 2011 (as shown in Figure 10).

**Figure 10.** Time series deformation comparison between georobot and InSAR, (a) monitoring point TP04; (b) monitoring point TP08.

5. Discussion

5.1. Landslide Type

For further analysis of the spatiotemporal deformation characteristics of the landslide, the cumulative time-series deformation along profile EE’ is abstracted and superimposed on the geological cross-section map, shown in Figure 11. As the interferograms are divided into three subsets, the third subset from 20090901 to 20110307 is selected for the time series deformation analysis. The earliest SAR acquisition date of the third subset is taken as the reference date, labeled as 20090901 in Table 1. The numbers in Figure 11 indicate the accumulated days from the reference date.

The thickness of the landslide can be deduced from borehole, adit and sonic wave data from 45 to 100 m [51,59]. The thickness in the front of section ranges from 90 to 130 m; in the middle section, ranges from 80 to 90 m; and in the rear section, ranges from 45 to 60 m. According to its material composition and geological structure, the landslide can be divided into 3 layers from bottom to top, that is, (i) Gravel with a small amount of silt (Qpl+col), which distributes in the front and middle ancient gullies of the sliding body, with a thickness ranging from 30 to 64 m; (ii) Clastic soil of the phyllite (Qdel), with a thickness ranging from 16 to 45 m; (iii) Dolomite gravel with a small amount of silt, which is widely distributed in the upper part of the slide mass, with a thickness ranging from 20 to 61 m. Geological reconnaissance showed the landslide belongs to the pull-type landslide, and the sliding surface is located in the lower part of the clastic soil of the phyllite formation (Qdel), the clastic soil of the phyllite and the gravel with a small amount of silt retrogressive creeping along the sliding surface [59]. As shown in Figures 6 and 8, the deformation occurred mainly in the Section II area and gradually increased with decreasing landslide height, which further confirms that the landslide belongs to the pull-type landslide.
Figure 11. Cumulative InSAR time-series deformation results and geological cross-section map along the profile EE’ (indicated in Figure 8). The reference SAR acquisition date in the third subset is September 1, 2009, and the different cumulative days from the reference date are shown in different colors. 1—Clastic soil of the phyllite; 2—Dolomite gravel with a small amount of silt; 3—Gravel with a small amount of silt; 4—Phyllite; 5—Marble; 6—Stratigraphic boundary; 7—Bedrock boundary; 8—Fault. (Geological cross-section map is modified after Xu [59]).

Three inclinometers were placed in Section II of Jinpingzi landslide, so the inner displacement of the landslide was obtained [51]. However, the monitoring period was different between InSAR and inclinometers, so the closest InSAR monitoring period to the inclinometer monitoring period was chosen for rough comparison (as shown in Table 2). Inner displacement shows that the depth of this landslide is mainly at around 55 m beneath the surface, which can be defined as the sliding surface [51]. It can also be seen that the inner deformation was larger than that at the surface, and the deformation in the leading section was larger than that at the tailing section for both the surface and inner point. Accordingly, it can be deduced that this landslide belongs to a pull-type landslide.

Table 2. The comparison between the inner and surface downslope deformation rate of Section II of Jinpingzi landslide (borehole data are cited from Wang et al. [51] and Xu [59]).

<table>
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<td>IN06</td>
<td>61</td>
<td>2009.10.10–2009.11.7</td>
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5.2. Environmental Factor Analysis

The activity of landslide is often affected by several environmental factors such as rainfall, soil moisture and river water level changes [61–66]. The correlation among precipitation, soil moisture, water level changes of the Jinsha River and the Jinpingzi landslide deformation rate is analyzed.

Firstly, 20 ALOS/PALSAR data are used to measure water level changes. As shown in Figure 11, the different SAR intensity images can reflect the water level changes, and it can be found that the water level in the rainy season is obviously higher than that in the dry season. To this end, all SAR intensity images are used to measure the water level changes according to the waterline and local terrain in different dates. Since the water body in SAR intensity shows low back scatter characteristics, the water level can be easily detected, as shown in red in Figure 12.
Secondly, the backscattering coefficient of the SAR intensity image is used to inverse the soil moisture changes, as the increase in soil moisture results in an increase in radar backscattering [67]. In sparsely vegetated areas, the backscattering coefficient can be expressed as

\[ \sigma_0 = \Gamma(0) h(\theta) g(s, l) \] (1)

where \( \sigma_0 \) is the backscattering coefficient, \( h(\theta) \) depends on the incidence angle \( \theta \), \( g \) is the surface roughness function, \( s \) is the surface \( \text{rms} \), \( l \) is the surface correlation length, \( \Gamma(0) \) is the Fresnel reflectivity, which can be expressed as

\[ \Gamma(0) = 0.0579 + 1.0263 M_v \] (2)

where \( M_v \) is the soil volumetric moisture. Therefore, in the case of the same incident angles, the backscattering coefficient of SAR intensity images mainly depends on the surface roughness and soil moisture. As changes in surface roughness would modify the relative positions of the scatter within each pixel, which will affect both the intensity and the phase information of the backscattering signal, coherence can be used as a reflection of surface roughness change [68]. We calculated the average SAR intensity of the area with a coherence value more than 0.65 for each selected interferograms (as shown in Figure 2) to inverse the soil moisture change. Then, the landslide deformation, rainfall, soil moisture and water level changes are analyzed.

Figure 13 shows the correlation among Jinsha River water level changes, monthly precipitation and daily deformation rate acquired by InSAR and georobot for the monitoring points TP08 and TP04, where error bars of the InSAR monitoring in the vertical component represent the uncertainty of the InSAR slip rate, and in the horizontal direction represent the time interval between two adjacent SAR acquisition dates. Some conclusions can be drawn as follows:

(i) The fluctuation of the water level in the Jinsha River is almost similar in each year during the monitoring period. The water levels of the reservoir area in July and August 2010 are the same as those in July and August 2007, but the landslide deformation in 2007 is much larger than that in 2010, which indicates that the fluctuation of the Jinshajiang river water is not the main influential factor of the landslide movement.

(ii) Qualitatively, the SAR intensity in the rainy season is obviously higher than that in the dry season, which means that the SAR intensity can reflect the surface soil moisture to a
certain extent. Accordingly, certain correlation between surface soil moisture and the total precipitation can be found, but there is a weak correlation between surface soil moisture and the landslide deformation.

(iii) During the rainy season, the monitoring result obtained from both georobot and InSAR is more sensitive to heavy precipitation events than to the total precipitation volume. As shown in Figure 14, the groundwater recharge of Section II is mainly from rainfall and the groundwater from Section I [51]. The aquifer of Section II is located at the lower part of the third layer (Qcol) and the upper part of the second layer (Qdel), so the underground water is blocked by slip band soil which is located under the aquifer, and is discharged as a spring at the leading edge of Section II [59]. As measured at the spring, the total discharge of groundwater is about 230 m³/d, and normally, the amount of the supplement and the discharge of the groundwater in this section are in a state of balance [59]. We suggest that when heavy rainfall occurs, the total amount of groundwater recharge is larger than the groundwater discharge, resulting in more water entering the sliding surface, which on the one hand decreases the shear strength of the landslide [65] and on the other hand increases the weight of the landslide. As a consequence, the landslide velocity will increase.

(iv) The maximum deformation of the landslide was highly consistent with the peak precipitation with a time lag of about 1 to 2 months. Quantitatively, the correlations of deformation and precipitation at the two monitoring points are only 0.3 and 0.4, respectively. If a one-month time lag is considered, the correlations increase to 0.56 and 0.55, respectively. However, due to the long ALOS/PALSAR satellite revisit time, it is difficult to identify the fine lag time between heavy precipitation and landslide onset. This finding can be verified with periodic in-situ three dimensional measurements [60].

Figure 13. The correlation among Jinsha River water level variations, monthly precipitation and daily deformation rate acquired by InSAR and georobot for the monitoring points (a) TP08 and (b) TP04, where error bars of the InSAR monitoring on the Y-axis represent the uncertainty of the slip rate in the selected regions, and horizontal bars of the InSAR monitoring on the X-axis represent the time interval between the adjacent SAR acquisition dates. (Monthly precipitation data are cited from reference [59]).
6. Conclusions

The processes of landslide identification and monitoring by InSAR methods are presented, among which four key steps are outlined. The annual deformation rate map in line-of-sight direction generated with the IPTA InSAR technique is used for landslide identification, and 22 suspected landslides located on two sides of Jinsha River valley are identified over an area more than 2500 km²; it can be deduced that water erosion is the landslide mechanism. The SBAS InSAR technique is applied to achieve time-series deformation maps over Section II of Jinpingzi landslide. This landslide deformation is controlled by the faults, geological formation and geomorphological structure. Considerable evidence, including surface and inner deformation features, indicates that this landslide belongs to a pull-type landslide. High InSAR deformation monitoring accuracy is obtained by the InSAR method in the comparison with in-situ georobot measurements, and the maximum downslope deformation rate reached 39 cm/y. The deformation of the landslide was very sensitive to heavy precipitation, and a 1- to 2-month time lag between the peak of the precipitation and the maximum deformation rate has been revealed. As a next step, and in order to better understand the movement of the landslide and its potential for further movement (a) the location of the slip surface must be identified, (b) the soil type along the slip surface will be detected and (c) the soil strength along the slip surface will be measured and/or estimated by back analyses using the recently proposed approach proposed by Stamatopoulos and Di and Di et al [69,70].

Our research provides a systematic procedure with the InSAR technique for landslide inventory mapping, deformation monitoring, trigger factor verification and landslide mode deductions, which will be beneficial to early warning system development for remote mountainous landslides under abnormal rainfall conditions.

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