A CONDITIONAL PROPERTY OF ADAPTIVE ESTIMATORS

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SUMMARY

In adaptive estimation, it is often considered that an
estimator has made a mistake if the component estimator
chosen for use is not the most efficient for the distribution
sampled.   Theoretical and simulation results point to a
fallacy in this line of thought.   The Monte Carlo study involves
extension of the Princeton Swindle to distributions con-
ditional on a location- and scale-free statistic, and to the
uniform.   The results give a partial explanation for the
sometimes surprising robutness of adaptive L-estimators.

Keywords:- Adaptive estimation; conditional reference sets; Monte Carlo
swindles; robustness

1.   INTRODUCTION

There has been a great deal of recent interest in the use of adaptive
estimators to achieve the goals of robust estimation.   Hogg (1974) gives
a broad perspective on the state of the art from one of the field's
pioneers.   Adaptive estimators may be roughly characterized as follows.

A "preliminary" statistic (Hogg's Q as defined below, the sample
kurtosis, or perhaps some combination of skewness and tailweight measures)

is calculated from the data, and used to select an estimator T from a class $\{T_\lambda, \lambda \in \Lambda\}$. Typically, the preliminary statistic is a sample measure of a population characteristic known to affect drastically the relative behavior of the T_λ.

The motivation for our study of the behavior of estimators conditional on a preliminary statistic is best understood by means of an example. Let the adaptive estimator T (for the point of symmetry of a symmetric population) be defined by

$$T = \begin{cases} T(.10) & \text{if } Q < 2.0 \\ T(.25) & \text{if } Q \geq 2.0 \end{cases}$$

where

$$T(\alpha) = \begin{cases} \text{median} & \alpha = .5 \\ \dfrac{1}{n-2[n\alpha]} \displaystyle\sum_{i=[n\alpha]+1}^{n-[n\alpha]} X_{(i)} & 0 \leq \alpha < .5 \\ \dfrac{1}{2\{[n(\alpha+.5)]+1\}} \displaystyle\sum_{i=1}^{[n(\alpha+.5)]+1} (X_{(i)} + X_{(n-i+1)}) & -.5 < \alpha < 0 \\ \text{midrange} & \alpha = -.5 \ , \end{cases}$$

$X_{(i)}$ (i = 1, ..., n) are the sample order statistics, and

$$Q = \frac{\bar{U}(.05) - \bar{L}(.05)}{\bar{U}(.5) - \bar{L}(.5)} \ ,$$

$\bar{U}(\alpha)$ and $\bar{L}(\alpha)$ being the average of the largest and smallest $[n\alpha]$ order statistics respectively. Note that, for $\alpha < 0$, $T(\alpha) = \frac{1}{2}\{\bar{U}(|\alpha|) + \bar{L}(|\alpha|)\}$. Q is thus a location- and scale-free tailweight

measure. (Population values are 1.95, 2.58, and 3.30 for the uniform,
normal, and double exponential, respectively.)

The usual presumption has been that if one is sampling from an
extremely heavy-tailed distribution and observes a sample with Q < 2.0,
hence using T = T(.10), a 10% trimmed mean instead of a 25% trim, an
error has been made. The following work demonstrates, however, that it
is quite possible that although

$$\text{Var}_{\text{Cauchy}}(T(.10)) > \text{Var}_{\text{Cauchy}}(T(.25)) ,$$

and also, in fact,

$$\text{Var}_{\text{Cauchy}}(T(.10)|Q < 2.0) > \text{Var}_{\text{Cauchy}}(T(.25)|Q < 2.0) ,$$

T(.25) may be much less inefficient with respect to T(.10)
when sampling from the conditional distribution, given Q < 2.0. This would
agree with the view that samples from the Cauchy with Q < 2.0 are more
uniform- or normal-like than their unconditional counterparts.

2. SOME THEORETICAL INSIGHTS

In this section we consider the case where K is a location- and scale-
free statistic, T is an unbiased location estimator (i.e. $T[a\underline{X} + b\underline{1}] = aT[\underline{X}] + b$ for $a \neq 0$), and the sampling is from a location family,
i.e. $f_\theta(x) = f(x - \theta)$ for all $x \in R$. If a complete and sufficient
statistic for θ exists, we let T_{cs} denote the unbiased estimator of θ which
is a function of it.

Then,

$$\text{Var}(T|K) = \text{Var}(T - T_{cs} + T_{cs}|K)$$

$$= \text{Var}(T - T_{cs}|K) + \text{Var}(T_{cs}|K)$$

$$= E\{(T - T_{cs})^2|K\} + \text{Var}(T_{cs})$$

by Basu's theorem, since the distribution of $T - T_{cs}$ is parameter free.
(Note that Basu's theorem works for the conditional distributions because
T_{cs} and K are statistically independent, as are T_{cs} and $T - T_{cs}$.)
Thus, we see that

(i)   If $T \equiv T_{cs}$, i.e. if our estimator is a function of a
complete and sufficient statistic, then the conditional
variance (in fact the entire distribution) of T is the
same as the unconditional.

(ii) A reasonable measure of the extent the conditional
variance of T depends upon $\tilde{K}$ would be

$$\text{Var}[E \{(T - T_{cs})^2|K\}] = \tau$$

and τ would be made large by a dependence between K
and $|T - T_{cs}|$, together with the possibility of large
values of $|T - T_{cs}|$.

Based upon these two considerations, we expect the conditional variances
to vary from the unconditional primarily for estimators T which are
of low efficiency and for conditioning variables K which truly reflect
characteristics which are related to the efficiency of T.

3. SIMULATION METHODS AND RESULTS

Several points regarding the Monte Carlo methods used in this study are of interest. It is desired to estimate the variances of $T(\alpha)$ for several values of α, at the normal, $.75N(0,1) + .25N(0,9)$, and uniform distributions, conditional on observing Q in specified ranges, for samples of size 20. (Note $.75N(0,1) + .25N(0,9)$ is not a true distribution, but a pseudo-sample consisting of 15 observations from $N(0,1)$ and 5 from $N(0,9)$.)

The first point is that, for those distributions where the Princeton Swindle is applicable, the extension to those distributions conditional on a location- and scale-free statistic is immediate. If $X_i = Z_i/Y_i$ $(i = 1, \ldots, n)$ where the Z_i are iid $N(0,1)$ and the Y_i are such that $P[Y_i = 0] = 0$ $(i = 1, \ldots, n)$, then $a = \Sigma Z_i Y_i / \Sigma Y_i^2$ and $b = [\{\Sigma Z_i^2 - (\Sigma Z_i Y_i)^2 / \Sigma Y_i^2\}/(n - 1)]^{\frac{1}{2}}$ are, conditional upon $\underline{Y}$, statistically independent of $\underline{c} = (\underline{x} - \underline{1}a)/b$. Therefore, if K is a location and scale free statistic, it is a function of $\underline{c}$ and thus independent of a and b, which yields

$$\text{Var}(T|K) = E[a^2] + \text{Var}(T(\underline{c})|K)$$

by the usual manipulations. Thus, we will estimate the conditional variance $\text{Var}(T|K)$ by

$$\hat{\text{Var}}(T|K) = E[a^2] + \frac{1}{M} \sum_{i=1}^{M} T^2(\underline{c}_i) \,,$$

where we have simulated the unconditional distribution N times, of which M satisfied the conditioning criterion. Arguments similar to those of Gross (1973) and Simon (1976) demonstrate that this swindle can only serve to reduce Monte Carlo variability. For distributions representable

as N(0,1)/Independent, we will thus generate from the unconditional distribution 10000 samples, estimating the various conditional quantities desired based upon those of the 10000 samples meeting the criterion.

The Princeton Swindle has not, however, been extended to short-tailed distributions. Nevertheless, an analogous variance reduction technique is available for any location-scale family admitting a two-dimensional complete and sufficient statistic (a,b), where a is a location statistic $\{a(c_1\underline{x} + c_2\underline{1}) = c_1 a(\underline{x}) + c_2, \quad c_1 \neq 0, \quad -\infty < c_2 < \infty\}$, and b is a scale statistic $\{b(c_1\underline{x} + c_2\underline{1}) = |c_1|b(\underline{x}), \text{ for } c_1 \neq 0, \text{ all } -\infty < c_2 < \infty\}$. Under these conditions, and with K as above,

$$\text{Var}(T|K) = E[a^2] + E[b^2] E[T^2(\underline{c})|K] ,$$

which permits essentially the same procedure as when the Princeton Swindle applied. Thus, in the case of sampling from a uniform distribution on the interval (-1,1),

$$\text{Var}(T|K) = \frac{2}{(n+1)(n+2)} + \frac{n(n-1)}{(n+1)(n+2)} E[T^2(\underline{c})|K] .$$

It should be noted that the savings due to the swindle in this case will be $O(\frac{1}{n^2})$ (order of the theoretically calculated term), an order in n higher than $E[T^2(\underline{c})|K]$ for most estimators. However, for near-efficient estimators, especially those with $E[T^2(\underline{c})|K] = O(\frac{1}{n^2})$, the gains will be especially valuable for small n. In independent work, Beal (1974) has also extended the Princeton Swindle to the case of a two-dimensional complete and sufficient statistic (a,b) with a a location statistic and b a scale statistic, but not to the case of conditioning upon a location- and scale-free statistic.

Normal pseudorandom variates were generated by means of the polar method, with a multiplicative congruential uniform generator used to obtain

pseudorandom uniforms. Tables 1, 2, and 3 give estimated variances for n = 20

of T(α) for α = -.5, -.4, -.25, 0, .05, .10, .25, and .50, conditional

on Q < 2.0, 2.0 ≤ Q ≤ 2.6, 2.6 < Q, and unconditionally for the N(0,1),

.75N(0,1) + .25N(0,9), and U(-1,1) respectively. These ranges correspond

roughly to the categories for Q used in T_1 of Hogg(1974), the first,

second and third categories containing the population values for the

uniform (1.95), normal (2.58), and double exponential (3.30) respectively.

The entries are n × (estimated variance), followed in parentheses by an

estimate of the standard error of these simulated values. The bottom

row in each table gives the number of the 10000 samples falling into the

conditional or unconditional category.

(Tables 1, 2, and 3 about here)

Several points emerge as worthy of note from an examination of these

tables. First is that our suggestions from section 2 hold true. The

highly efficient estimators (trims with small α for N(0,1), α near

.25 for .75N(0,1) + .25N(0,9), and α near -.5 for U(-1,1)) exhibit only

small or no deviations of their conditional variances from their

unconditional variances. However, highly inefficient estimators (α near

-.5 for N(0,1) or .75N(0,1) + .25 N(0,9), and α near .5 for U(-1,1))

deviate greatly in this regard. For instance, the midrange (α = -.5),

while having an unconditional variance over 19 times that of T(.25)

for .75N(0,1) + .25N(0,9), has the same ratio approximately equal to 2.7

conditional on Q < 2.0. Thus, usage of T(-.5) wherever Q < 2.0 would be

not nearly as serious an error in this sampling situation as its uncon-

ditional behavior would suggest. Similar observations hold for other

comparisons.

A further use of these results (and, more generally speaking, this sampling methodology) would be to assess the behavior of possible adaptive estimators without extensive costly Monte Carlo studies. For instance, for the estimator

$$T = \begin{cases} T(-.5) & Q < 2.0 \\ T(0) & 2.0 \leq Q \leq 2.6 \\ T(.5) & 2.6 < Q \end{cases}$$

(admittedly not a terribly informed choice) we estimate the variance at $N(0,1)$ (all variances still multiplied by 20, the sample size) to be

$$\hat{Var}(T) = \frac{935}{10000}(1.578) + \frac{6648}{10000}(1.000) + \frac{2417}{10000}(1.372) = 1.144 .$$

Similarly, at $.75N(0,1) + .25N(0,9)$ T would have estimated variance 2.283 and at $U(-1,1)$ it would have estimated variance .211. An analysis incorrectly ignoring the conditional behavior (taking the same linear combination as above but using the unconditional variances) would have estimated these three variances as 1.287, 2.732, and .176. Thus, we see that for the first two distributions, an assessment based upon unconditional behavior drastically underrates the adaptive estimator. The situation is, however, reversed for the (admittedly extreme) uniform distribution. Thus we see that naive assessment of adaptive estimators may well seriously misestimate (generally overestimate) their variances.

4. SUMMARY AND CONCLUSIONS

Theoretical and Monte Carlo results are given to suggest that the reason for the surprising robustness of adaptive estimators may lie in the unsuspectedly good conditional behavior of their components. To

facilitate efficient simulation, variance reduction methods were extended to the relevant conditional situations. The results provide a method for assessing more accurately and efficiently the behavior of prospective robust adaptive estimators.

5. ACKNOWLEDGMENT

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TABLE 1

Estimated Conditional Variances of $T(\alpha)$ when Sampling from $N(0,1)$

	α	Q < 2.0	$2.0 \leq Q \leq 2.6$	2.6 < Q	Unconditional
Midrange	-.5	1.578 (.025)	2.408 (.024)	4.096 (.067)	2.871 (.027)
	-.4	1.411 (.019)	1.790 (.014)	2.167 (.027)	1.876 (.012)
	-.25	1.158 (.007)	1.190 (.003)	1.180 (.004)	1.184 (.003)
Mean	0.0	1.000 (.000)	1.000 (.000)	1.000 (.000)	1.000 (.000)
	.05	1.007 (.000)	1.017 (.000)	1.038 (.000)	1.023 (.000)
	.10	1.026 (.001)	1.049 (.001)	1.073 (.002)	1.055 (.001)
	.25	1.158 (.007)	1.190 (.003)	1.180 (.004)	1.184 (.003)
Median	.50	1.621 (.027)	1.490 (.009)	1.372 (.009)	1.464 (.006)
# Repetitions		935	6648	2417	10,000

TABLE 2

Estimated Conditional Variances of $T(\alpha)$ when
Sampling from $.75N(0,1) + .25N(0,9)$

	α	$Q < 2.0$	$2.0 \leq Q \leq 2.6$	$2.6 < Q$	Unconditional
Midrange	-.5	5.045 (.509)	13.474 (.387)	39.934 (.529)	34.610 (.443)
	-.4	4.812 (.501)	10.999 (.327)	20.929 (.277)	18.856 (.234)
	-.25	3.530 (.350)	5.592 (.155)	6.616 (.080)	6.382 (.070)
Mean	0.0	2.334 (.139)	2.992 (.056)	3.056 (.026)	3.034 (.023)
	.05	2.192 (.115)	2.550 (.041)	2.253 (.015)	2.307 (.014)
	.10	2.059 (.091)	2.221 (.030)	1.883 (.010)	1.948 (.010)
	.25	1.879 (.063)	1.952 (.020)	1.766 (.007)	1.803 (.007)
Median	.50	2.122 (.094)	2.286 (.031)	2.070 (.012)	2.111 (.011)
# Repetitions		138	1864	7998	10,000

TABLE 3

Estimated Conditional Variances of $T(\alpha)$ when Sampling from $U(-1,1)$

	α	$Q < 2.0$	$2.0 \leq Q \leq 2.6$	$2.6 < Q$	Unconditional
Midrange	-.5	.087 (.000)	.087 (.000)	.087 (.000)	.087 (.000)
	-.4	.099 (.000)	.122 (.001)	.241 (.016)	.108 (.001)
	-.25	.157 (.001)	.253 (.004)	.482 (.044)	.192 (.002)
Mean	0.0	.282 (.003)	.434 (.008)	.676 (.071)	.336 (.003)
	.05	.328 (.004)	.516 (.010)	.815 (.087)	.395 (.004)
	.10	.378 (.005)	.591 (.012)	.866 (.094)	.452 (.005)
	.25	.553 (.007)	.767 (.016)	.979 (.109)	.627 (.007)
Median	.50	.844 (.012)	.922 (.020)	1.086 (.132)	.872 (.011)
# Repetitions		6641	3250	109	10,000

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In adaptive estimation, it is often considered that an estimator has made a mistake if the component estimator chosen for use is not the most efficient for the distribution sampled. Theoretical and simulation results point to a fallacy in this line of thought. The Monte Carlo study involves extension of the Princeton Swindle to distributions conditional on a location- and scale free statistic, and to the uniform. The results give a partial explanation for the sometimes surprising robustness of adaptive L-estimators.

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