Discussion of Dr. Silverman's Paper

by

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Technical Report No. SMU-DS-TR-190 Department of Statistics ONR Contract

December 1984

Research sponsored by the Office of Naval Research Contract N00014-82-K-0207 Project NR 042-479

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Contribution to the

Discussion of Dr. Silverman's Paper

October 1984

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Let me begin by thanking Professor Silverman for an interesting and thought-provoking paper. His use of regression type diagnostics for smoothing splines coincides with many of my own thoughts on this subject (Eubank 1984a, b). The close connection between smoothing splines and polynomial regression leads one to believe that diagnostics appropriate for use with smoothing splines should resemble those currently in use by regression analysts. In this regard, it is well known that diagnostic procedures should include information about the design as well as the fit. Design diagnostics for smoothing splines are provided by the leverage values, $A_{11}(\alpha)$. It can be shown that $0 \leq A_{11}(\alpha) \leq 1$ and that a leverage value too near one indicates a sensitive point in the design where an observation will tend to dominate its own fit. A diagnostic which encompasses both information about an observation's leverage as well as its fit is (in Silverman's notation)

DFITS₁ = $|A_{11}(\alpha)/(1-A_{11}(\alpha))|^{\frac{1}{2}}|r_1|$, i=1,...,n. This particular diagnostic indicator can be motivated from analogous quantities used in regression analysis and can provide valuable information over that available from measures focusing on residuals alone. Many other regression type diagnostics can also be suggested. Concerning interval estimation, there are several alternatives to Silverman's method based on sample estimates of the influence curve for smoothing splines. One of these (c.f. Wold 1971) can be described as follows. For simplicity assume that $w_i=1,i=1,\ldots,n$, and let $\hat{g}[i]$ and $\hat{v}[i]$ denote the smoothing spline estimate and vector of coefficient estimates, under the B-spline basis, when (t_i,Y_i) has been deleted from the data. It can be shown that

$$\underline{\hat{v}}^{[\mathbf{i}]} = [\alpha \Omega + B^{T}B]^{-1}B^{T} \left[\underline{Y} - \underline{\mathbf{e}}_{\mathbf{i}} \frac{(Y_{\mathbf{i}} - \hat{g}(\mathbf{t}_{\mathbf{i}}))}{1 - A_{\mathbf{i}\mathbf{i}}(\alpha)} \right],$$

where $\underline{e_i}$ is the ith column of the n×n identity matrix, which gives $\hat{g}^{[i]}(t) = \sum_{j=1}^{n} \hat{v}_j^{[i]} \beta_j(t)$. Given a functional Ψ we then define pseudo-values

$$P_{i}(\Psi) = \Psi(\hat{g}) - (n-1)(\Psi(\hat{g}) - \Psi(\hat{g}^{[i]}))$$
, $i=1,...,n$,

and obtain the jackknife variance estimate (Efron 1982)

$$S_{\Psi}^{2} = [n(n-1)]^{-1} \sum_{i=1}^{n} (P_{i}(\Psi) - \overline{P}(\Psi))^{2}$$

where $\overline{P}(\Psi) = n^{-1} \sum_{i=1}^{n} P_i(\Psi)$. An approximate 95% confidence interval for $\Psi(g)$ is provided by $\Psi(\hat{g}) \pm 2S\Psi$. The computation of S_{Ψ}^2 simplifies considerably when Ψ is linear. Professor Silverman's approximations for the $A_{i,j}(\alpha)$ have some obvious applications to jackknife interval estimation.

Jackknife confidence intervals do not require the assumption of normal errors and are more computationally expedient than the Bayesian approach when **Y** is nonlinear. It should also be noted (see e.g. Hinkley 1977) that jackknife methods might be expected to be robust against nonhomogenous error variances. It would be interesting to compare jackknife methods to Silverman's approach with estimated weights in this setting.

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REPORT NUMBER		2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER	
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Contribution to the Discussion of Dr. Silverman's Paper		f Dr.	Technical Report	
		6. PERFORMING ORG. REPORT NUMBER		
AUTHOR(=)		B. CONTRACT OR GRANT NUMBER(*)		
Randall L. Eubank		N00014-82-K-0207		
PERFORMING ORGANIZATION NAME AND ADDRESS Department of Statistics		10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS		
Southern Methodist University , Dallas, Texas 75275				
		NR 042-479		
. CONTROLLING OFFICE NAME AND ADDRESS			12. REPORT DATE	
Office of Naval Research Arlington, VA 22217				
		•	13. NUMBER OF PAGES	
MONITORING AGENCY NAME & ADDRESS(II different from Controlling Office)		15. SECURITY CLASS. (of this report)		
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